
Recent Challenges of Auto-tuning: Accuracy Optimization and Explainable AI

Takahiro Katagiri

(Information Technology Center, Nagoya University)

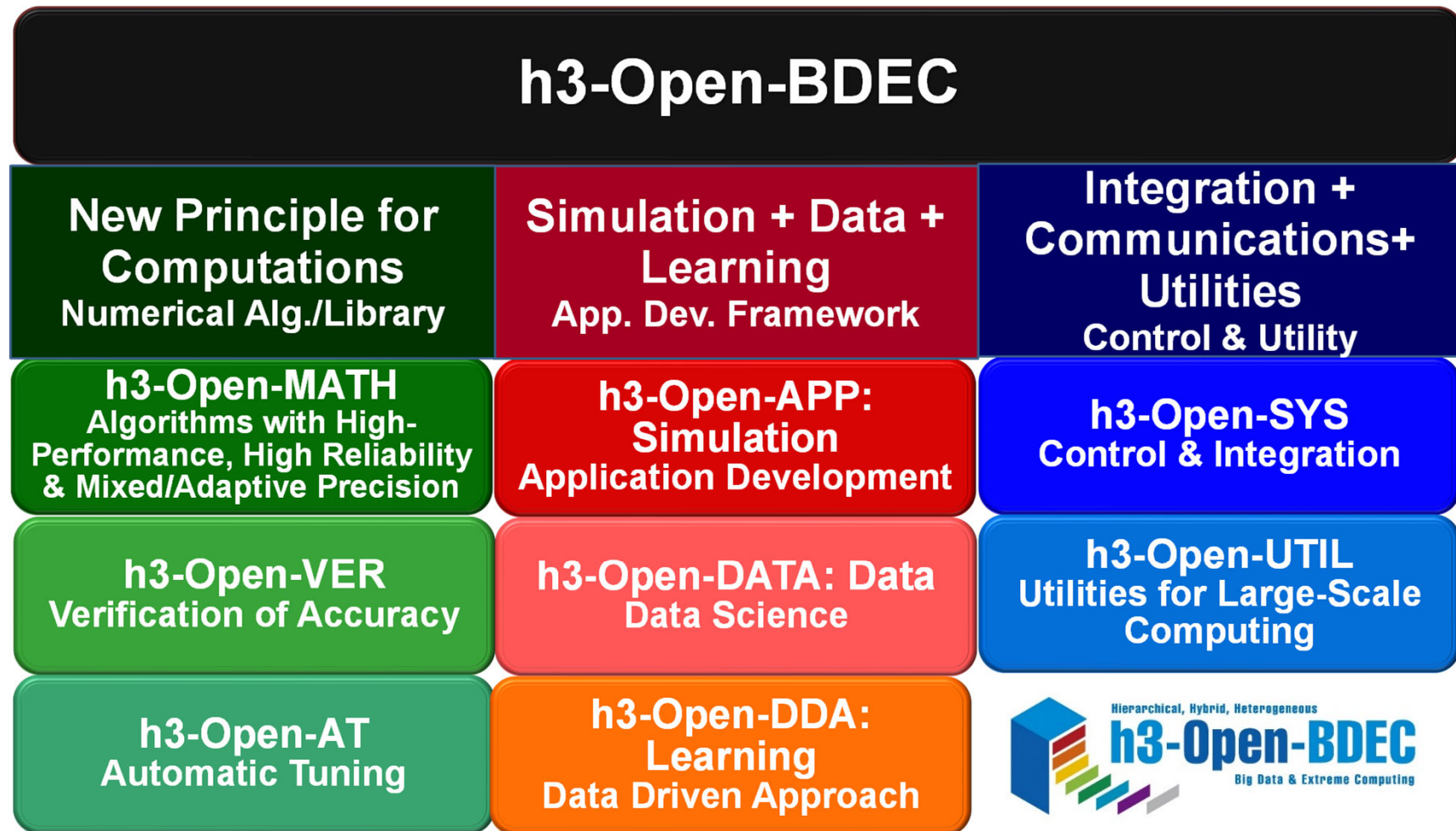
International Workshop on the Integration of (Simulation + Data + Learning) Towards Society
5.0 by h3-Open-BDEC, Nov. 30 & Dec. 3, 2021

Session 3 (3 Dec 8:40~9:00 JST) Adaptive precision, AT & Verification (II)



h3-Open-BDEC

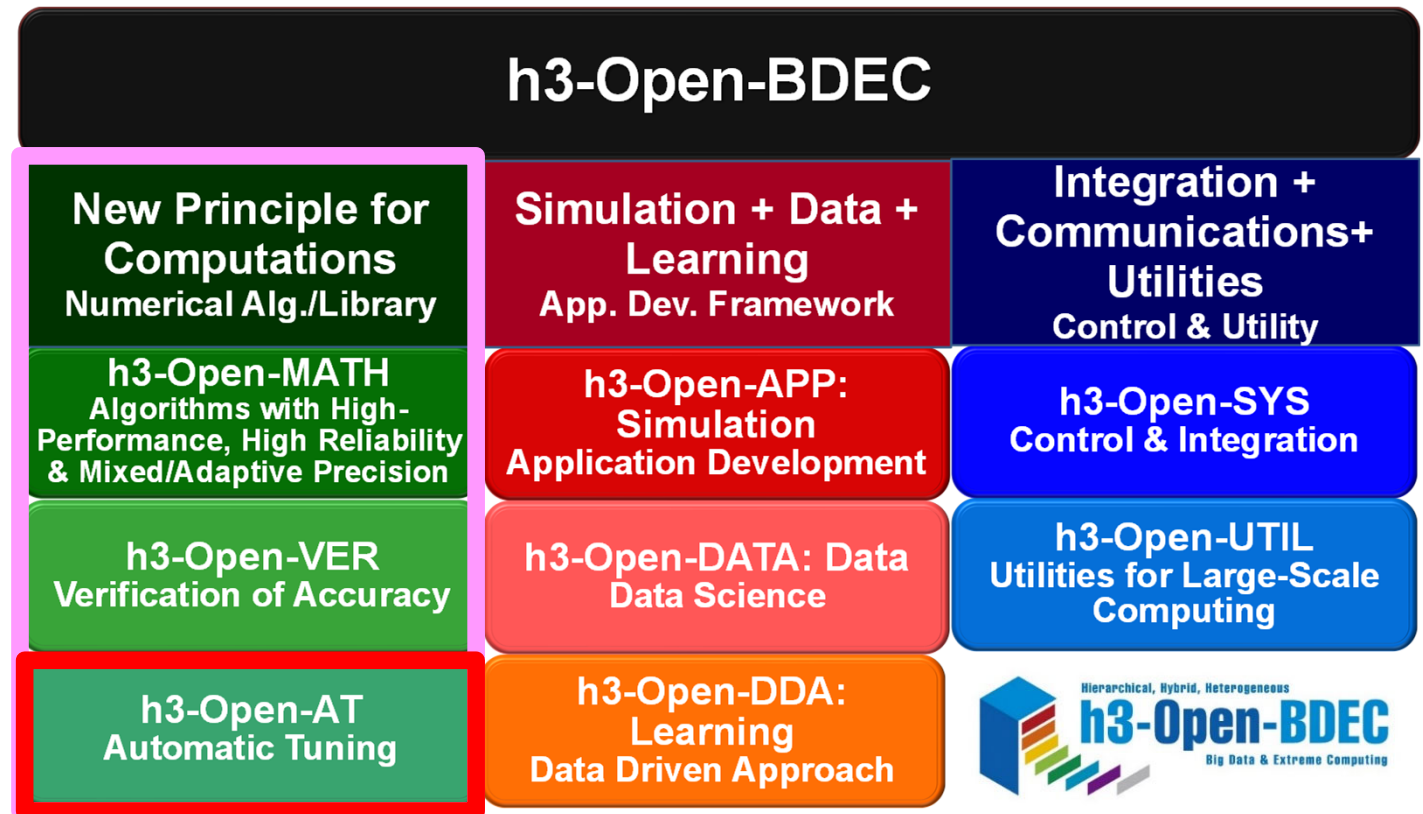
Innovative Software Platform for Integration of (S+D+L) on BDEC



h3-Open-BDEC: Two Significant Innovations

① Methods for Numerical Analysis with High-Performance/High-Reliability/Power-Saving based on the New Principle of Computing by

- ✓ Adaptive Precision
- ✓ Accuracy Verification
- ✓ **Automatic Tuning**



Outline

▶ Main issues in this talk:

1. How to reduce cost of tuning for mixed-precision computations and/or energy consumption?

▶ Answer: Use AT framework!

2. Is AI result of tuning on numerical libraries reliable?

▶ Answer: Use Explainable AI (XAI)! → Scientific XAI (SXAI)

▶ TOPIC I

▶ Mixed-Precision and Energy Optimization by ppOpen-AT

▶ TOPIC II

▶ Explainable AI for Auto-tuning on an Accurate Precision Matrix-Matrix Multiplication Library

Outline

▶ TOPIC I

- ▶ Mixed-Precision and Energy Optimization by ppOpen-AT

▶ TOPIC II

- ▶ Explainable AI for Auto-tuning on an Accurate Precision Matrix-Matrix Multiplication Library



Collaboration with

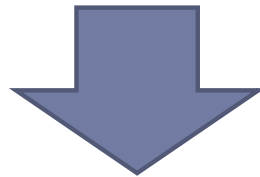
- **Mr. Shohei Yamanashi**, Master Course Student, Graduate School of Informatics, Nagoya University
- **Dr. Hisashi Yashiro**, Center for Global Environment Research, National Institute for Environmental Studies

A Proposal of Mixed-Precision and/or Energy Optimization for ppOpen-AT



Background

- ▶ More complex computer architectures are being designed toward to era of Post Moore:
 - ▶ Multi-cores on CPUs, Deep hierarchies for memory, **Low precision computations**, Quantum Computing, etc.



- ▶ **Mixed Precision Computations**
 - ▶ Low precision computation (single/half) is applied for a part of computations in programs.

⇒ Obtaining **speedup and low energy**.



Aim of this study

- ▶ Automation of performance tuning for mixed precision computation by adapting **Software Auto-tuning (AT) Technology** [I-1].
- ▶ The followings are targets in mixed precision computations in this research:
 1. **Variables / Arrays**
 2. **Blocks**
 3. **Functions / Sub routines**
- ▶ New directives of AT for the above are proposed for ppOpen-AT.

[I-1] Takahiro Katagiri, Daisuke Takahashi, Japanese Autotuning Research: Autotuning Languages and FFT, Proceedings of the IEEE, Volume: 106, Issue: 11, Nov. 2018, pp. 2056-2067 (2018).



An AT Language: ppOpen-AT[1-2]

- ▶ AT language to add AT functions to programs.
- ▶ Code generator makes the followings automatically:
 1. Multiple candidates of optimized code.
 2. Search program for AT to find the best candidate.

```
!oat$ install unroll (i) region start
!oat$ varied (i) from 1 to 4
do i = 1 , n
  do j = 1, n
    do k = 1, n
      A(i, j) = A(i, j) + B(i, k) * C(k, j)
    enddo; enddo; enddo
!oat$ install unroll (i) region end
```

Code
Generation

```
do i = 1, (n/3)*3, 3
  do j = 1, n
    do k = 1, n
      A(i,j) = A(i,j) + B(i,k) * C(k,j)
      A(i+1,j) = A(i+1,j)+B(i+1,k)*C(k,j)
      A(i+2,j) = A(i+2,j)+B(i+2,k)*C(k,j)
    enddo; enddo; enddo
  if (mod(n, 3) /= 0) then
    do i = (n/3)*3+1, n
      do j = 1, n
        do k = 1, n
          A(i, j) = A(i, j) + B(i, k) * C(k, j)
        enddo; enddo; enddo
    endif
```

Ex) Loop unrolling from 1st to 4th depths.

Ex) loop unrolling with 3rd depth.

[1-2] 片桐孝洋, ppOpen-AT: ポストペタスケール時代の数値シミュレーション基盤ソフト,
数理解析研究所講究録 第1791巻, pp. 107-111 (2012).



Process Flow for AT of Mixed-Precision Computations and/or Energy

- “Users” are defined by:
- Software Developers;
 - End-Users;

The following slides explain each step.

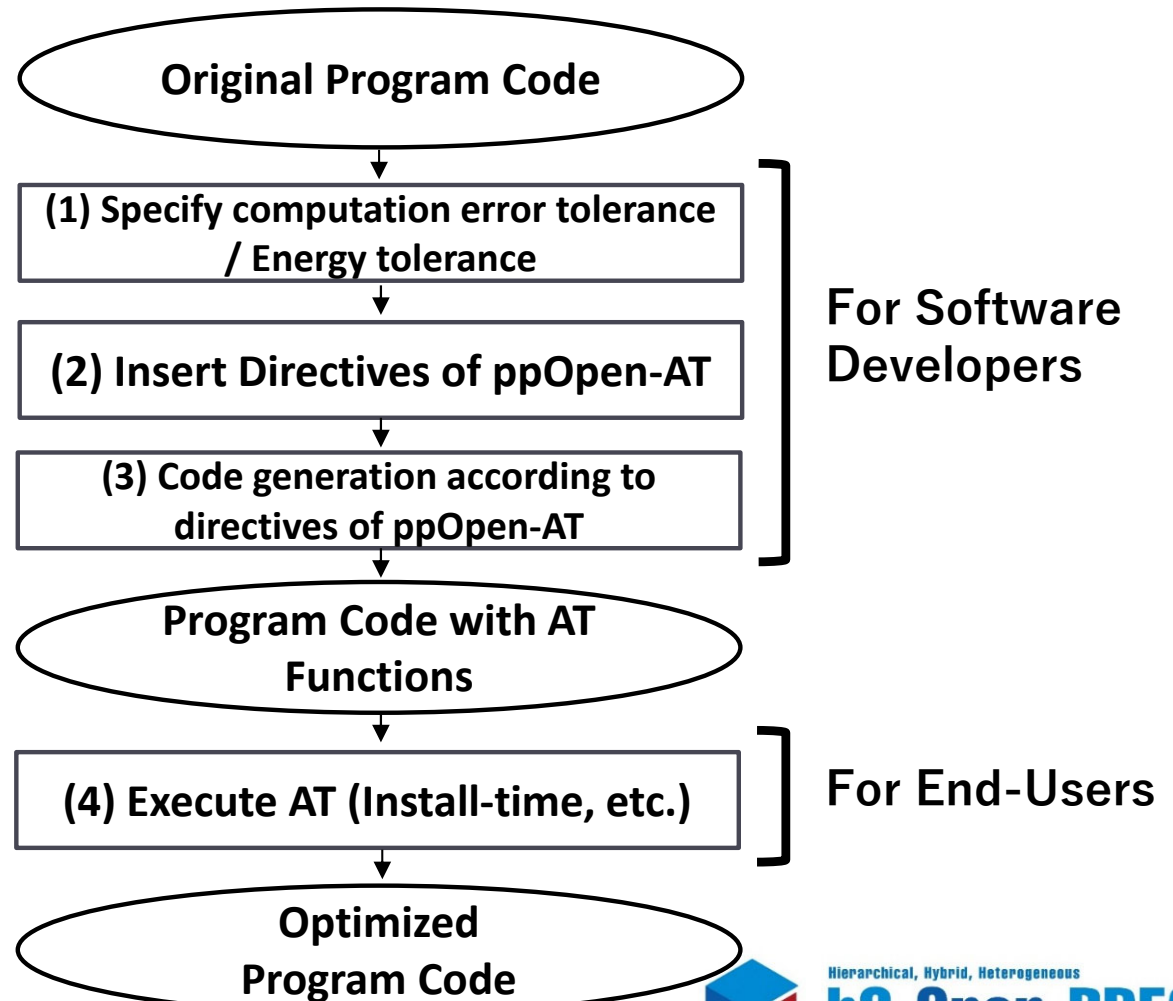


Fig: Process Flow for the Proposal AT



(1) Specify computation error tolerance / Energy tolerance

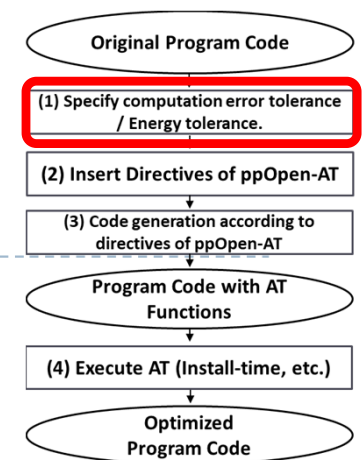
▶ Software Developers specified the following by using directives of ppOpen-AT.

▶ Computation Error Tolerance

- ▶ Specify a tolerance error ratio from original computations (such as double precision) to mixed-precision computations (such as double and single precisions)
- ▶ Ex) $1e-7$ in relative error. The AT system tries to optimize program code within $1e-7$ in relative error.

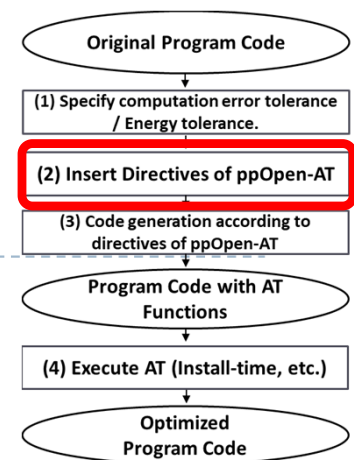
▶ Energy Tolerance

- ▶ Specify a tolerance ratio to energy from original computations (such as double precision) to mixed-precision computations (such as double and single precisions)
- ▶ Ex) less than 10% energy reduction to energy of original code.



(2) Insert Directives of ppOpen-AT

The following directives is inserted to original program by software developers.



1. Variables / Arrays

```
!oat$ MixedPrecision variables, [clause . . . ]
    {structured-block}
!oat$ end MixedPrecision variables
```

2. Blocks

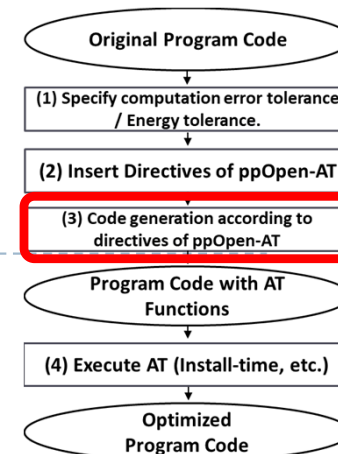
```
!oat$ MixedPrecision blocks, [clause. . . ]
{
!oat$ MixedPrecision block <num>
    {structured-block}
!oat$ end MixedPrecision block <num>
. . .
}
!oat$ end MixedPrecision blocks
```

3. Functions / Sub routines

```
!oat$ MixedPrecision subprogram, [clause . . . ]
    {structured-block}
!oat$ end MixedPrecision subprogram
```



(3) Code generation according to directives of ppOpen-AT



1. Variables / Arrays

Cantates codes are generated by the directives.

Preparation copies (overhead) are needed.

```
!oat$ MixedPrecision variables, ¥  
ChangeVariables(B(:, :), C(:, :)), ¥  
ChangePrecision(DP, SP)  
do i = 1, n  
  do j = 1, n  
    do k = 1, n  
      B(i, k) = B(i, k) + 2.0_DP  
      C(k, j) = C(k, j) + 2.0_DP  
      A(i, j) = A(i, j) + B(i, k) * C(k, j)  
    enddo; enddo; enddo  
!oat$ end MixedPrecision variables
```

Example of Directives for Variables / Arrays.

```
real(SP) :: B_SP(n,n)  
real(SP) :: C_SP(n,n)  
  
B_SP(:, :) = B(:, :)  
C_SP(:, :) = C(:, :)  
  
!oat$ MixedPrecision variables, ¥  
ChangeVariables(B(:, :), C(:, :)), ¥  
ChangePrecision(DP, SP)  
do i = 1, n  
  do j = 1, n  
    do k = 1, n  
      B_SP(i, k) = B_SP(i, k) + 2.0_DP  
      C_SP(k, j) = C_SP(k, j) + 2.0_DP  
      A(i, j) = A(i, j) + B_SP(i, k) * C_SP(k, j)  
    enddo; enddo; enddo  
!oat$ end MixedPrecision variables  
  
B(:, :) = B_SP(:, :)  
C(:, :) = C_SP(:, :)
```

A Candidate Code for Single Precision Computations of Arrays B and C.



(3) Code generation according to directives of ppOpen-AT

2. Blocks

Cantates codes are generated by the directives.

Preparation copies (overhead) are needed.

Propagation Single-ization

```
!oat$ MixedPrecision blocks, ¥
ChangeBlocks(1),ChangePrecision(DP,SP)
do i = 1, n
  do j = 1, n
    do k = 1, n

      !oat$ MixedPrecision block <1>
      B(i, k) = B(i, k) + 2.0_DP
      C(k, j) = C(k, j) + 2.0_DP
      !oat$ end MixedPrecision block <1>

      !oat$ MixedPrecision block <2>
      A(i, j) = A(i, j) + B(i, k) * C(k, j)
      !oat$ end MixedPrecision block <2>

    enddo; enddo; enddo
  !oat$ end MixedPrecision blocks
```

Example of Directives for Blocks.

Block #1

Block #2

Code Generation

```
real(SP) :: B_SP(n,n)
real(SP) :: C_SP(n,n)

B_SP(:, :) = B(:, :)
C_SP(:, :) = C(:, :)

!oat$ MixedPrecision blocks, ¥
ChangeBlocks(1),ChangePrecision(DP,SP)
do i = 1, n
  do j = 1, n
    do k = 1, n

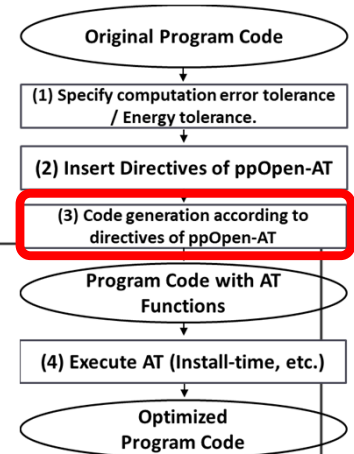
      !oat$ MixedPrecision block <1>
      B_SP(i, k) = B_SP(i, k) + 2.0_SP
      C_SP(k, j) = C_SP(k, j) + 2.0_SP
      !oat$ end MixedPrecision block <1>

      !oat$ MixedPrecision block <2>
      A(i, j) = A(i, j) + ¥
      B_SP(i, k) * C_SP(k, j)
      !oat$ end MixedPrecision block <2>

    enddo; enddo; enddo
  !oat$ end MixedPrecision blocks

B(:, :) = B_SP(:, :)
C(:, :) = C_SP(:, :)
```

A Candidate Code for Single Precision Computations of Block#1



(3) Code generation according to directives of ppOpen-AT

3. Functions/Subroutines

Candidate codes are generated by the directives.

Subroutine name is re-named with single precision.

Candidate Code (Callee)

```

! 呼び出し側(caller)
!oat$ MixedPrecision subprogram, ¥
caller(1), ChangePrecision(DP,SP)
call sample_subroutine(A(:,,:),B(:,,:),C(:,,:))
!oat$ end MixedPrecision subprogram

! 呼び出される側(callee)
!oat$ MixedPrecision subprogram, ¥
callee(1), ChangePrecision(DP,SP)
subroutine sample_subroutine(A,B,C)

implicit none
real(DP), intent(inout) :: A(n,n)
real(DP), intent(in) :: B(n,n)
real(DP), intent(in) :: C(n,n)

integer :: i,j,k

do i = 1, n
  do j = 1, n
    do k = 1, n
      B(i, k) = B(i, k) + 2.0_DP
      C(k, j) = C(k, j) + 2.0_DP
      A(i, j) = A(i, j) + B(i, k) * C(k, j)
    enddo; enddo; enddo

return
end subroutine sample_subroutine
!oat$ end MixedPrecision subprogram
    
```

Code Generation

```

! 呼び出し側(caller)
real(SP) :: A_SP(n,n)
real(SP) :: B_SP(n,n)
real(SP) :: C_SP(n,n)

A_SP(:, :) = A(:, :)
B_SP(:, :) = B(:, :)
C_SP(:, :) = C(:, :)

!oat$ MixedPrecision subprogram, ¥
caller(1), ChangePrecision(DP,SP)
call sample_subroutine_SP( ¥
  A_SP(:, :), B_SP(:, :), C_SP(:, :) )
!oat$ end MixedPrecision subprogram

A(:, :) = A_SP(:, :)
B(:, :) = B_SP(:, :)
C(:, :) = C_SP(:, :)
    
```

Candidate Code (Caller)

Code Generation

```

! 呼び出される側(callee)
public :: sample_subroutine_SP

!oat$ MixedPrecision subprogram, ¥
callee(1), ChangePrecision(DP,SP)
subroutine sample_subroutine(A,B,C)

implicit none
real(DP), intent(inout) :: A(n,n)
real(DP), intent(in) :: B(n,n)
real(DP), intent(in) :: C(n,n)

integer :: i,j,k

do i = 1, n
  do j = 1, n
    do k = 1, n
      B(i, k) = B(i, k) + 2.0_DP
      C(k, j) = C(k, j) + 2.0_DP
      A(i, j) = A(i, j) + B(i, k) * C(k, j)
    enddo; enddo; enddo

return
end subroutine sample_subroutine

subroutine sample_subroutine_SP(A_SP,B_SP,C_SP)

implicit none
real(SP), intent(inout) :: A_SP(n,n)
real(SP), intent(in) :: B_SP(n,n)
real(SP), intent(in) :: C_SP(n,n)

integer :: i,j,k

do i = 1, n
  do j = 1, n
    do k = 1, n
      B_SP(i, k) = B_SP(i, k) + 2.0_SP
      C_SP(k, j) = C_SP(k, j) + 2.0_SP
      A_SP(i, j) = A_SP(i, j) + ¥
        B_SP(i, k) * C_SP(k, j)
    enddo; enddo; enddo

return
end subroutine sample_subroutine_SP
!oat$ end MixedPrecision subprogram
    
```

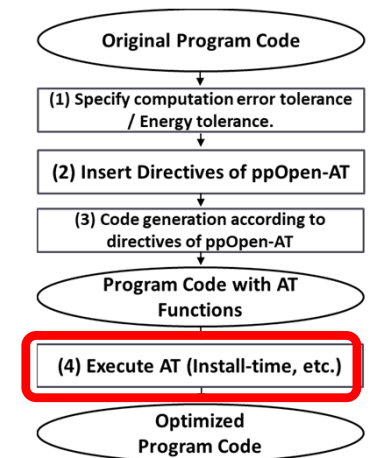
Example of Directives for Subroutines.

(4) Execute AT (Install-time, etc.)

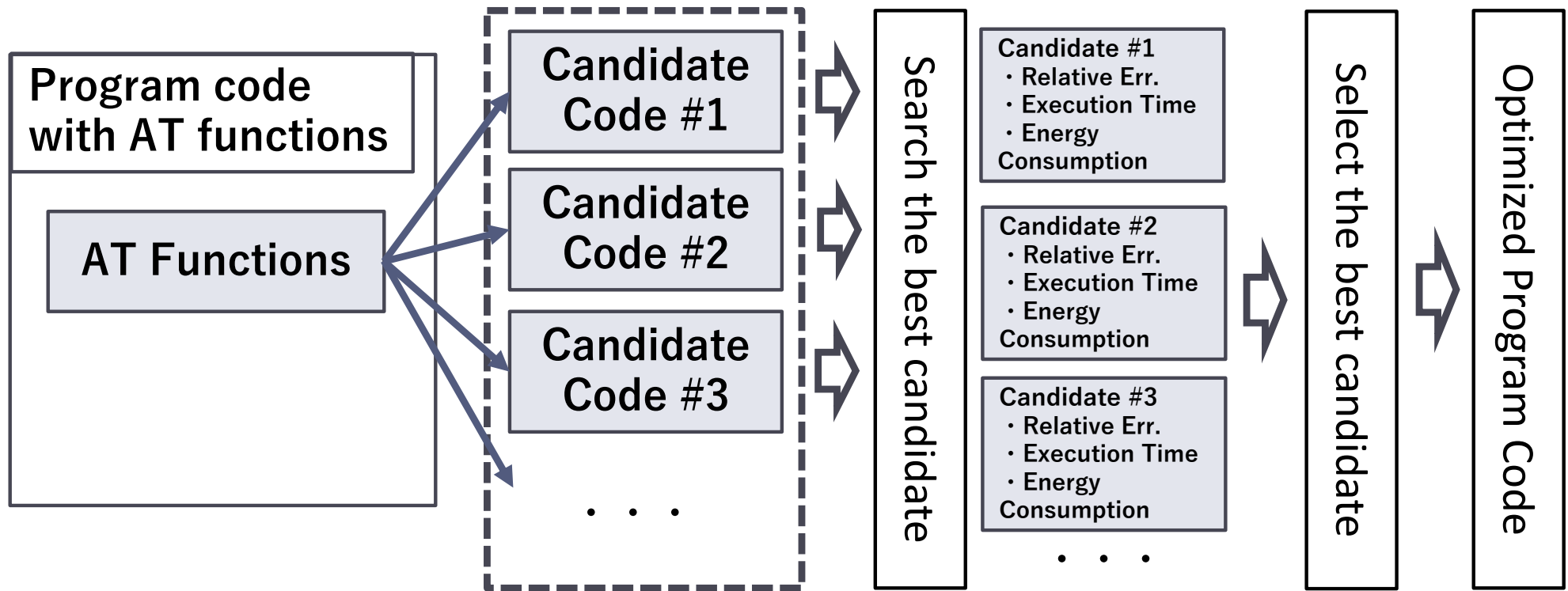
End-Users perform AT, like Install-time, etc.

In the AT, system tries to find the best candidate based on error tolerance and/or energy tolerance in the process (1).

(If there is no solution, the AT system reports it.)



- Error Tolerance
- Energy Tolerance

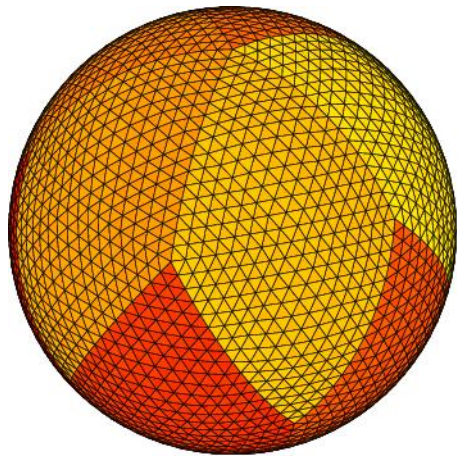


Target Application

■ Global cloud resolution model NICAM[1-3]

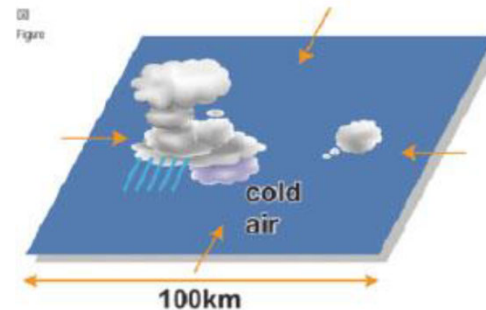
Non-hydrostatic Icosahedral Atmospheric Model.

Computational grids for earth atmosphere is introduced, then elements of weather factors are calculated in each grid.

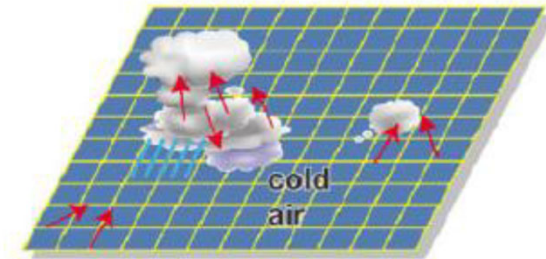


Source: What is NICAM?
https://cesd.aori.u-tokyo.ac.jp/satoh/nicam_comm.html

[1-3] Satoh, M., Tomita, H., Yashiro, H. et al. The Non-hydrostatic Icosahedral Atmospheric Model: description and development. Prog. in Earth and Planet. Sci. 1, 18 (2014).



Conventional Model



NICAM Model

Source: 富田浩文,京を使った高解像度全球大気シミュレーションの成果とこれからの展望



Target Program

- ▶ **nicam_dckernel_2016** [1-3]
 - : A package of benchmark for NICAM
 - ▶ A subroutine **mod_mp_nsw6.f90**, in physicskernel_microphysics on nicam_dckernel_2016.
 - ▶ **Physical computation of tiny cloud.**
- ▶ Characteristics of the target program
 - **Very long loop body** in the **three-nested loop**.
 - Loop count is fixed.
 - Output values are calculated inside the loop
 - **This indicates: sensitive for low precision computations for the output values.**

[1-3] https://github.com/hisashiyashiro/nicam_dckernel_2016



Condition of The Experiment

- ▶ 1. **Valuables/Arrays**, and 2. **Blocks**, are evaluated.

1. **Valuables/Arrays**

- **183 valuables/arrays** in the target programs are grouping into **13 groups**.
- Low precision-nize (Double to Single) are done in each group .

2. **Blocks**

- Target blocks in the target programs are split to **36 blocks**.
- Low precision-nize (Double to Single) are done in each block .



Details of the Experiment

▶ Execution Time

- The target three-nested loops

▶ Maximum Relative Error

$$\max \left\{ \left| \frac{\text{Output of DP} - \text{Output of changing computational accuracy}}{\text{Output of DP}} \right| \right\}$$

▶ Energy Consumption

- Energy of the target three-nested loop is measured.
- **PowerAPI [5] by Fujitsu Ltd. is used.**

[5] 富士通, “FUJITSU Software Technical Computing Suite V4.0L20 ジョブ運用ソフトウェア APIユーザーズガイド Power API編”, J2UL-2462-02Z0(01), 2020年6月



Computer Environment

The Supercomputer “Flow” Type I Subsystem,
Information Technology Center, Nagoya University

▶ “Fugaku” Type supercomputer



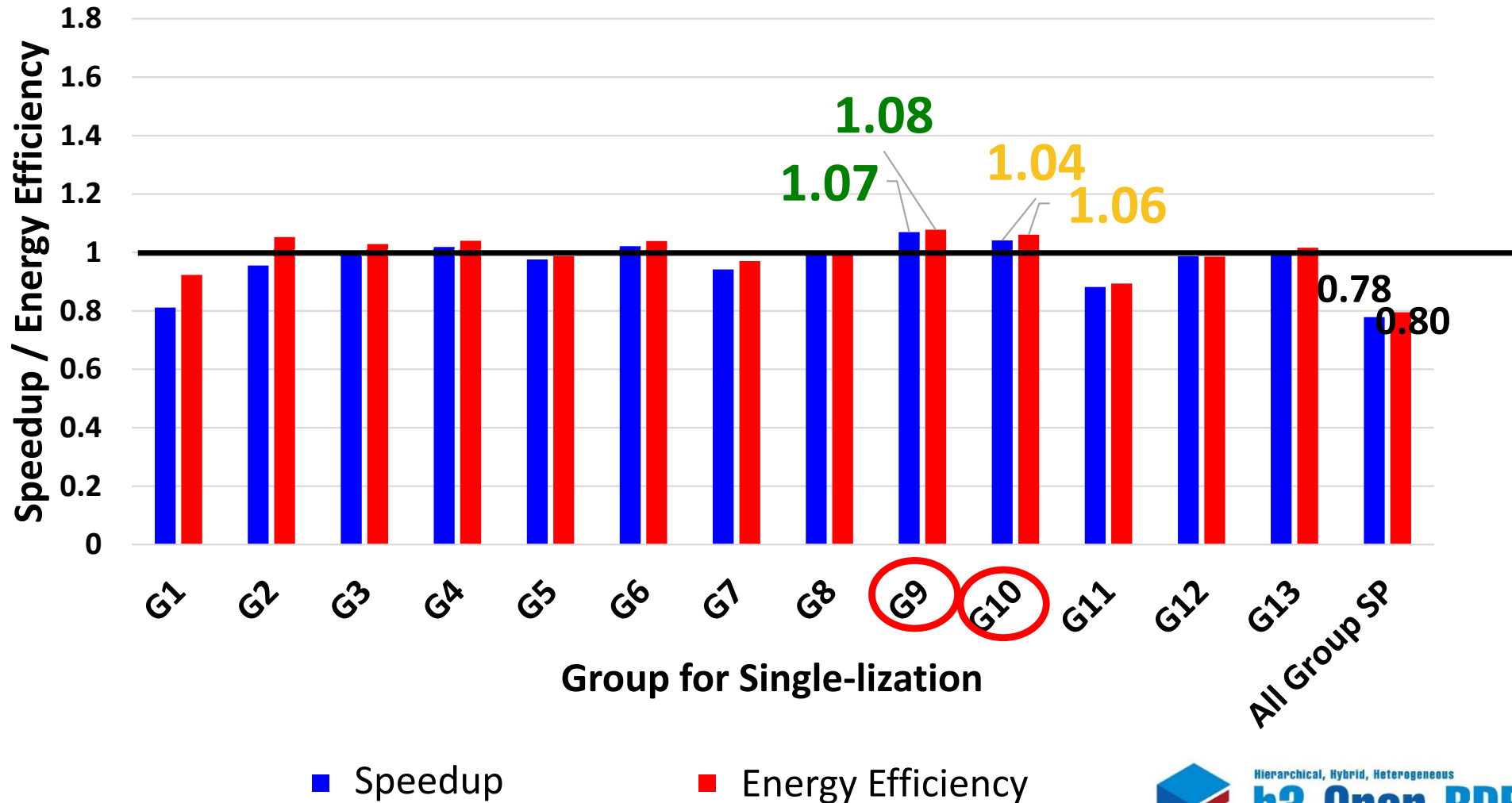
FUJITSU Supercomputer PRIMEHPC FX1000

| | |
|----------------------------------|--|
| Processor | A64FX (Armv8.2-A + SVE) |
| Number of Processor per Node | 1 |
| Number of Cores per Node | 48 Cores + 2 Assistant Cores |
| Frequency | 2.2GHz |
| Theoretical Performance per Node | Double precision: 3.3792 TFLOPS Single precision: 6.7584 TFLOPS Half precision: 13.5168 TFLOPS |

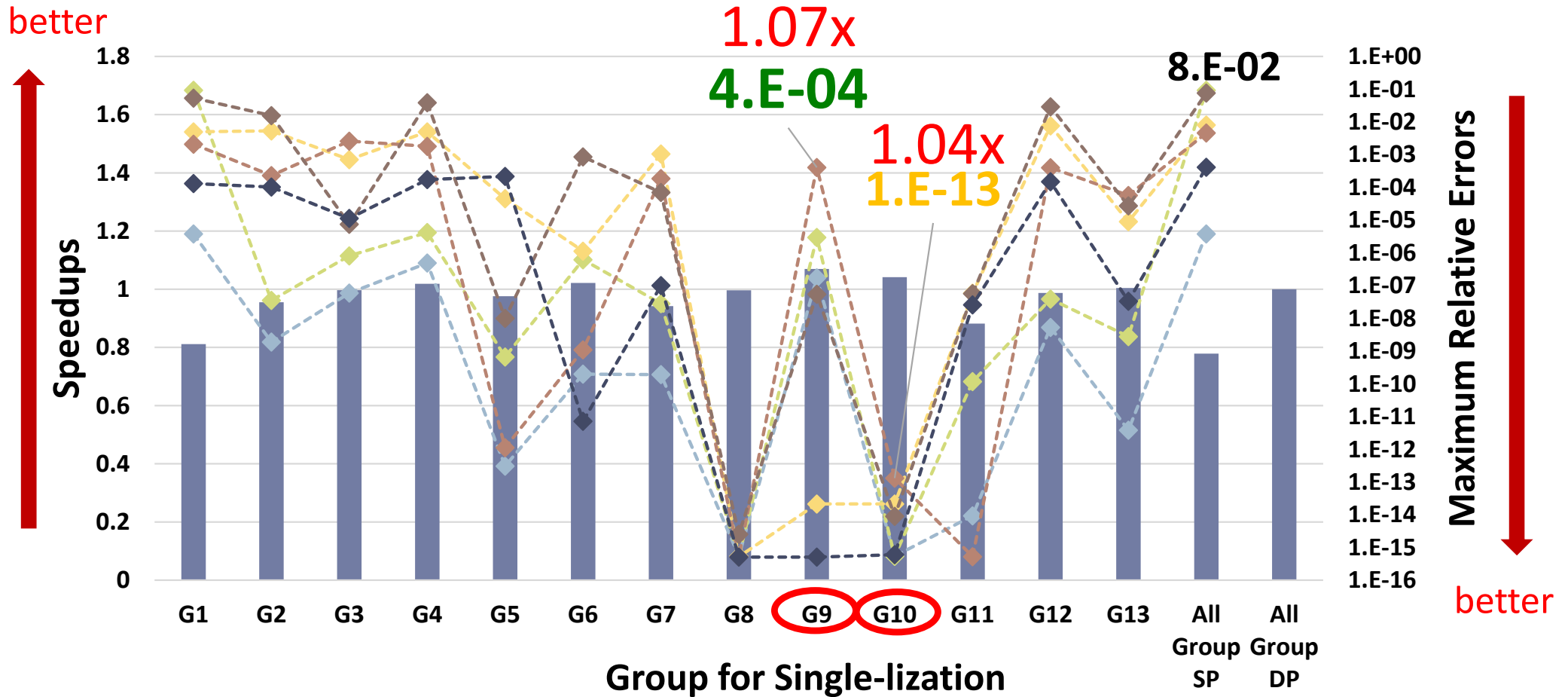
Software

| | |
|------------------|---|
| C | frtpx: Fujitsu Fortran Compiler 4.5.0 tcsds-1.2.31 |
| Compiler options | Kfast,ocl,preex,noalias=s,mfunc=2 -Nlst=i -Nlst=t -X03 -Ncompdisp -Koptmsg=2 -Cpp -Kdynamic_iteration -Ksimd,openmp -Kauto,threadsafe -x- -Kprefetch_sequential=soft - Nclang -L /opt/FJSVtcs/pwrm/aarch64/lib64 -lpwr |

Result of 1. Variables / Arrays: Speedup and Energy Reduction



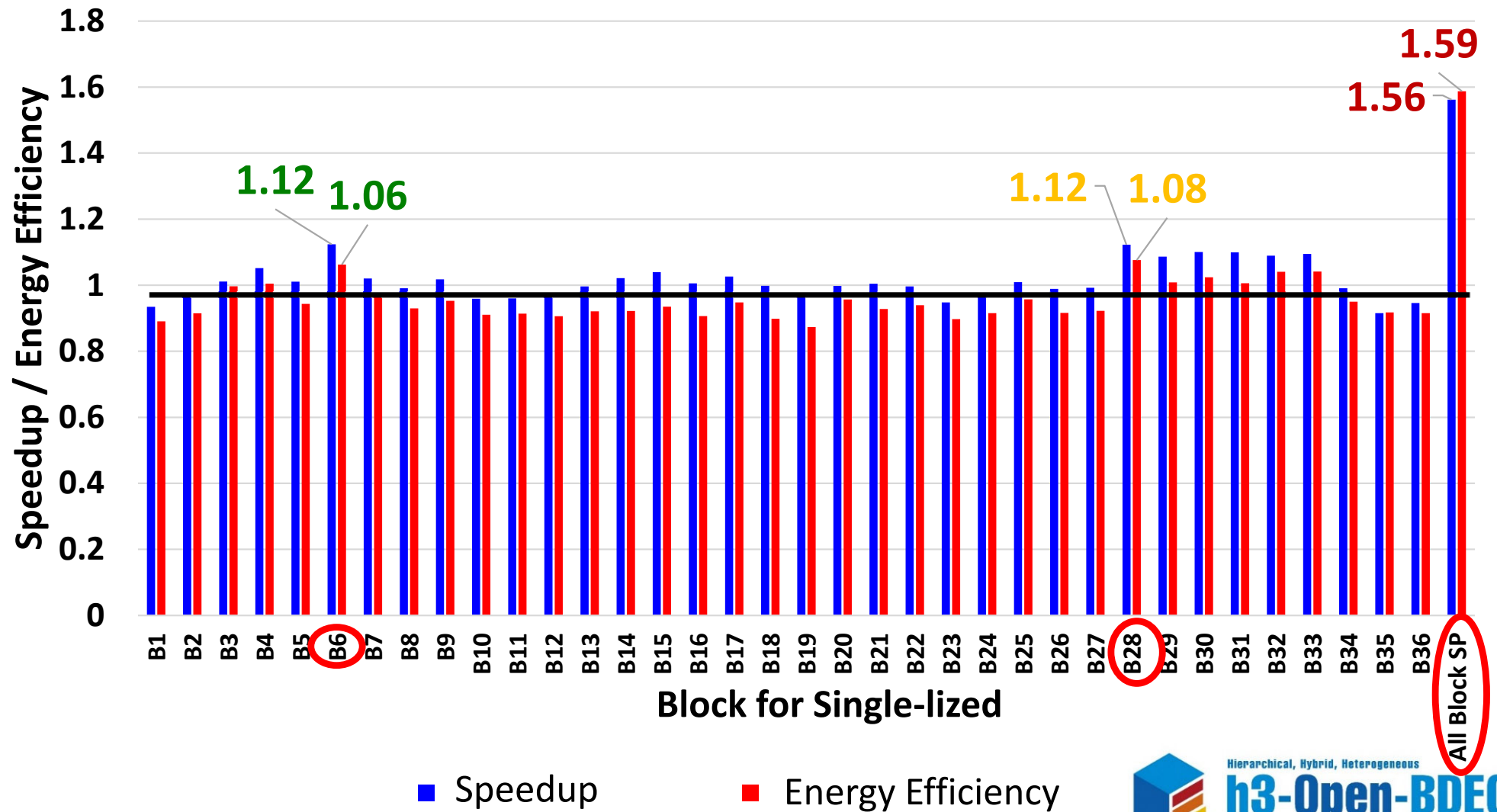
Result of 1. Variables / Arrays: Speedup and Maximum Relative Errors



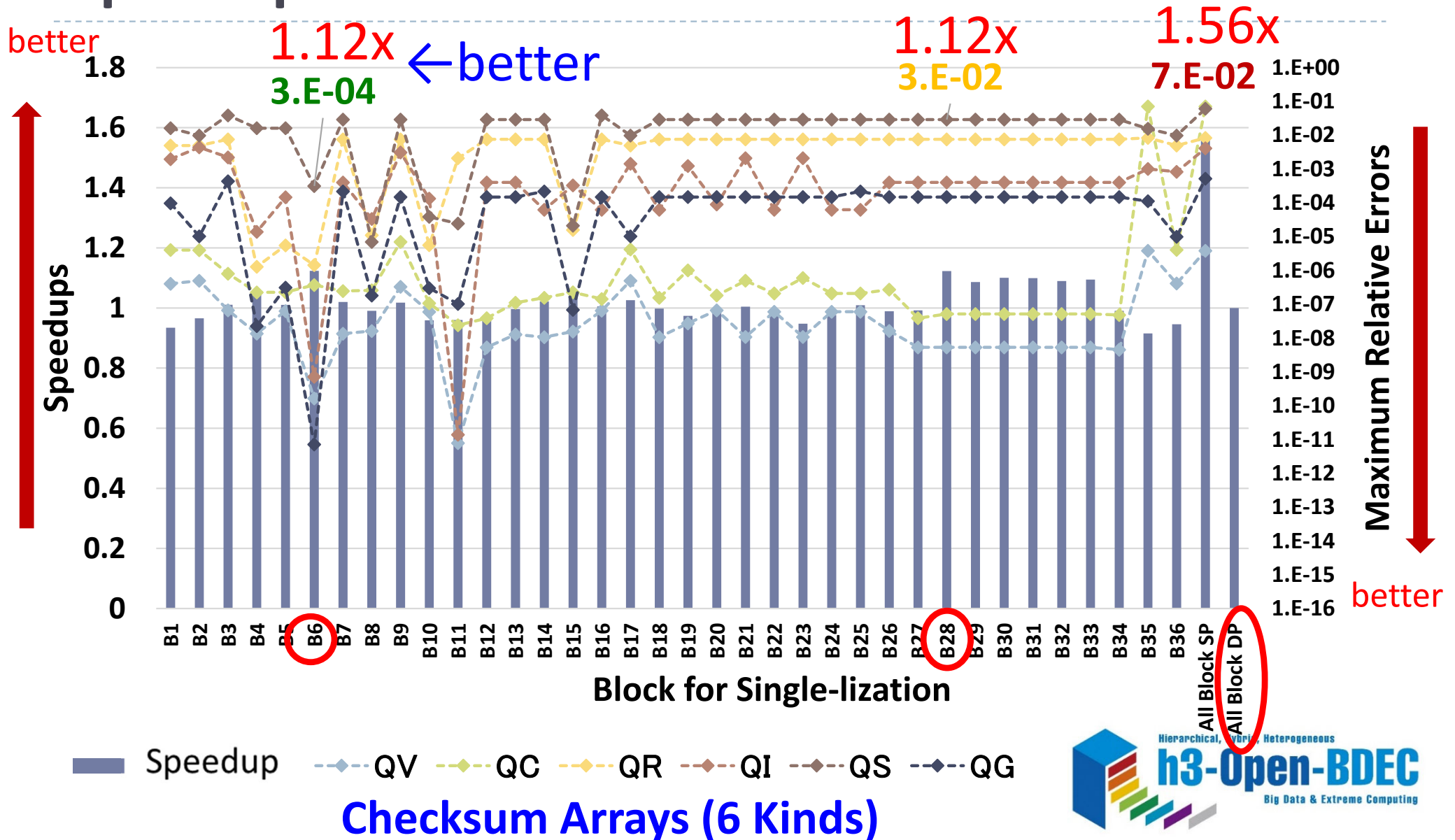
Checksum Arrays (6 Kinds)



Result of 2. Blocks: Speedup and Energy Reduction



Result of 2. Blocks: Speedup and Maximum Relative Errors



Outline

- ▶ TOPIC I

- ▶ Mixed-Precision and Energy Optimization by ppOpen-AT

- ▶ **TOPIC II**

- ▶ Explainable AI for Auto-tuning on an Accurate Precision Matrix-Matrix Multiplication Library



Collaboration with

[Mr. Shota Aoki](#), Master Course Student,
Graduate School of Informatics, Nagoya University

Explainable AI for Auto-tuning of Numerical Libraries



Background

- ▶ Several social problems occur due to **usage of results from artificial intelligence (AI) without verification.**
- ▶ Human check is needed from output from AI.
- ▶ To reduce cost of tuning process, several technologies of **software auto-tuning (AT)** is developing.
 - ▶ **Currently, AI is applied for the AT function.**
 - In this study, we **verify AI result** for performance tuning of **a numerical library for accuracy assurance** to show “explainability of AI output.”



Explainable AI (XAI)

- ▶ Can we explain output from AI?
 - ▶ Explainable AI (XAI)
- ▶ Explainable AI is classified as follows.[II-1]
 - ▶ **Explainability**
 - ▶ Technology for explanation of predicted results to help human understanding.
 - ▶ Ex) Tools for LIME, SHAP
 - ▶ **Interpretability**
 - ▶ Technology for understanding of computation process up to final prediction by analyzing inside data structures.
 - ▶ Ex) Making decision tree.

→ In this study, we focus on Explainability.

[II-1] 大坪ほか：「XAI(説明可能なAI)：そのとき人工知能はどう考えたのか」、リックテレコム、2021

SHAP (SHapley Additive exPlanations) [II-2]

- ▶ **Shapley Value** for collaborative game theory is applied.
 - ▶ There is validity.
- ▶ **Approximately** Shapley value is calculated.
 - ▶ **Ensemble model for tree** : High speed and accurate Shapley value.
 - ▶ **Deep learning model** : High speed and approximate Shapley value.
 - ▶ **General algorithms** : Estimated Shapley value.
- ▶ **Drawback**
 1. **High Computation Complexity**
→ Approximate value is only solution to use.

[II-2] S. Lundberg, S.-I. Lee, A Unified Approach to Interpreting Model Predictions, 2017
<https://arxiv.org/abs/1705.07874>



VNC-HPC Library

- Post-K Exploratory Research1: 基礎科学のフロンティアー極限への挑戦ー:「極限の探究に資する精度保証付き数値計算学の展開と超高性能計算環境の創成」 (PI: Prof. Takeshi Ogita at Tokyo Women's Cristian University, ~2019)
- Environment of high performance computing is developing to maintain computation accuracy.
- The following library is released as open source software.
 1. OzBLAS: Accurate and Reproducible BLAS based on Ozaki scheme [for PC, GPU]
 2. GEMMTC: GEMM using Tensor Cores [for GPU]
 3. DHPMM_F for GPU: High-precision Matrix Multiplication with Faithful Rounding [for GPU]
 4. PDDOTK: K-fold Precision Dot Product [for PC, FX100]
 5. BLAS-DOT2: Higher-precision BLAS based on Dot2 [for GPU]
 6. LINSYS_VR: Verified Solution of Linear Systems with Directed Rounding [for K Computer, FX100]
 7. LINSYS_V: Verified Solution of Linear Systems [for PC, K Computer, FX100]
 8. DHPMM_F: High-precision Matrix Multiplication with Faithful Rounding [for PC, K Computer, FX100]

The screenshot shows the VNC-HPC website with the following content:

- Verified Numerical Computations**
VNC-HPC
High-Performance Computing
- ポスト「京」萌芽的課題1**
基礎科学のフロンティアー極限への挑戦
極限の探究に資する精度保証付き数値計算学の展開と超高性能計算環境の創成
- Navigation tabs: トップページ (Top), 課題概要 (Abstract), 研究体制 (System), 研究内容 (Contents), 成果公開 (Results)
- リンク** (Links):
 - トップページ
 - 課題概要
 - 研究体制
 - 研究内容
 - 成果公開
- 課題概要** (Abstract):

本研究課題の目的は、ポスト「京」において、精度が保証された計算結果を実用的に得られるような超高性能計算環境を構築することです。具体的には、ポスト「京」で実行される様々な数値シミュレーションにおいて、数値計算による計算誤差の問題が解消されることによって、シミュレーションサイエンスの品質を向上させ、さらに想定外の現象が発生する可能性を低減することが可能となります。すなわち、本研究課題の遂行は、人が安心して生活できる社会基盤の構築に直結します。

たとえば、産業界における製品開発や非破壊検査等のための計算工学シミュレーションや、地震や津波などの災害シミュレーションは、日本に限らず世界中で盛んに行われていますが、計算誤差の観点から高精度なシミュレーションの実現をしている例は皆無です。これは、計算機によって問題の近似的な解を得ることよりも、その近似解の検証のほうがはるかに困難かつ計算資源を必要とする、と考えられており、それが高性能計算分野の常識であるからです。実際、これは1990年代までは事実でしたが、本研究グループが2000年代から切り拓いてきた高速で実用的な精度保証付き数値計算法やエラーフリー変換に基づく高精度数値計算法をベースとして、今、ポスト「京」によって、この常識を打ち破る時期が到来しています。すなわち、ポスト「京」において、高速性と高精度性を融合した超高性能計算環境の創成を世界に先駆けて達成することは、スーパーコンピュータに質的転換をもたらし、我が国の高い科学技術力を国内外に示すこととなります。
- 性能 = 速度 × 精度** graph:
 - Y-axis: 精度 (高信頼性) (Accuracy (High Reliability))
 - X-axis: 速度 (高速性) (Speed (High Speed))
 - Green arrow: エネルギー効率 (省エネ) (Energy Efficiency (Energy Saving)) with labels Green500, Green Graph500, ...
 - Blue arrow: 速度 (高速性) (Speed (High Speed)) with labels Top500, Graph500, ...
 - Red box: 本研究課題 (This Research Topic)
- Text below graph: 大規模数値計算を行う高性能計算分野においては、問題の大規模化に伴って計算誤差が累積しやすくなり、これが今後、大きな問題となってきます。たとえば、計算機上で標準的に用いられる32ビットの浮動小数点演算では、100万次元程度の密行列系線形問題に対して数値計算を行うと、問題自身は比較的良条件下で解きやすい問題であったとしても、誤差解析の結果から理論的には1桁も正しくないような計算結果が得られることが分かっています。また、計算誤差の単なる累積だけでなく、問題の困難さが条件数として

HP: <http://www.math.twcu.ac.jp/ogita/post-k/index.html>

Background, objective, and motivation of our work

- **High-accuracy and low-accuracy calculations** are one of the important calculation techniques which can solve large-scale and complicated calculations.
- Some studies have investigated the **accuracy assurance of BLAS and LAPACK**.
 - These studies have used mixed procedure computations and arbitrary digit computations.
 - Most of BLAS and LAPACK libraries tend to place **less emphasis on the accuracy of the computation results**.
- Why high-accuracy and assured calculations are not widespread?
- => **TIME**
- We consider to **calculate it on GPU and shorten the time**.
- This work will be helpful for large-scale and complicated calculations on current and future generation computers. (➡ **topics of interest** of this workshop)

In particular, we will focus on the following **topics of interest**, but not limited to:

- Programming models, languages and frameworks for facilitating HPC software evolution and refactoring.
- Algorithms and implementation methodologies for future-generation computing systems, including manycores and accelerators (GPUs, Xeon Phi, etc).
- Automatic performance tuning techniques, runtime systems and domain-specific languages for hiding the complexity of underlying system architectures.
- Practices and experiences on porting of legacy applications and libraries.

High-precision matrix-matrix multiplication algorithm

- Our target calculation: assured matrix-matrix multiplication (MMM) method proposed by Ozaki et al.
 - hereinafter, we refer to this MMM method as **the Ozaki method**
- Overview of the Ozaki method:

consider $C = AB$

- A : a matrix of size $m * l$
- B : a matrix of size $l * n$
- C : a matrix of size $m * n$

Step1: error-free transformation

$$A = A^{(1)} + A^{(2)} + A^{(3)} + \dots + A^{(p)}$$

$$B = B^{(1)} + B^{(2)} + B^{(3)} + \dots + B^{(q)}$$

The elements in the matrices with lower indices are given with a higher number of digits.

Step2: individual MMM

$$\begin{aligned} AB &= (A^{(1)} + A^{(2)} + \dots + A^{(p)})(B^{(1)} + B^{(2)} + \dots + B^{(q)}) \\ &= \underline{A^{(1)} B^{(1)}} + \underline{A^{(1)} B^{(2)}} + \underline{A^{(2)} B^{(1)}} + \dots + \underline{A^{(p)} B^{(q)}} \end{aligned}$$

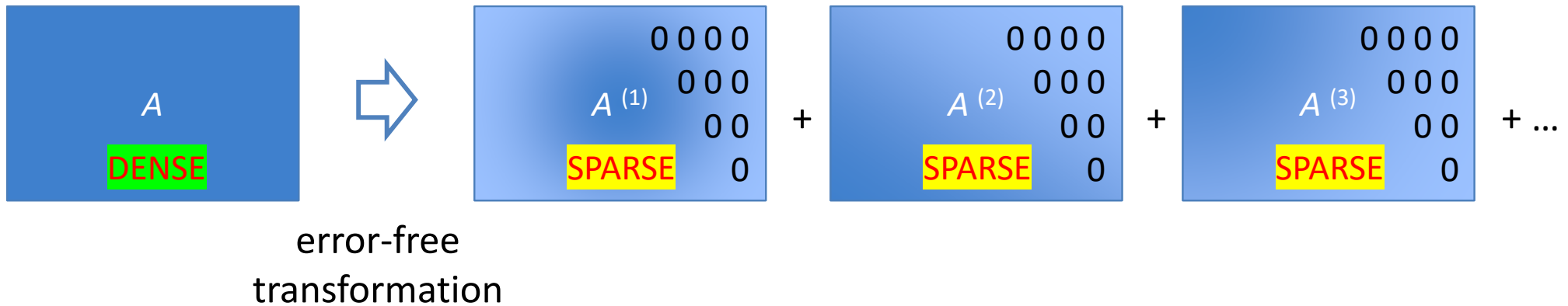
Step3: Accurate Sum

$$\begin{aligned} fl(A^{(i)} B^{(j)}) &= A^{(i)} B^{(j)} \text{ for } 1 \leq i \leq p, 1 \leq j \leq q. \\ &= fl(A^{(1)} B^{(1)}) + fl(A^{(1)} B^{(2)}) + fl(A^{(2)} B^{(1)}) + \dots \\ &\quad + fl(A^{(p)} B^{(q)}) \\ &= C_1 + C_2 + \dots + C_{pq} \end{aligned}$$

fl is a floating-point arithmetic with rounding to the nearest

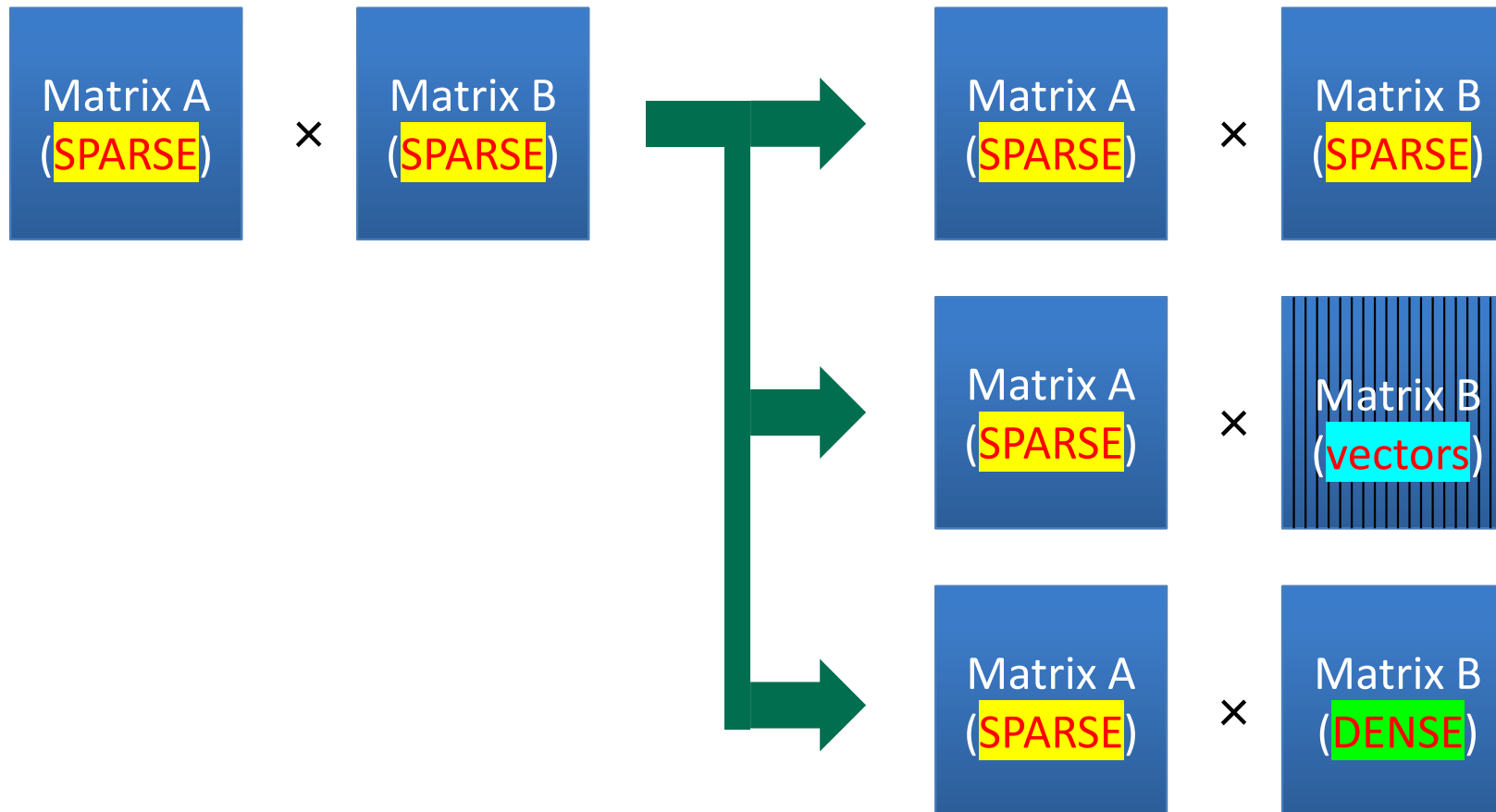
Previous work and Proposed method

- When the value ranges of the input matrix elements are large, error-free transformation generates many sparse matrices.



- In this case, many double precision general matrix - matrix multiplication (dgemm) are performed. Transforming dense matrices into sparse matrices and **performing sparse matrix operations will require shorter calculation time than dense matrix operations.**
- Therefore, our previous work proposed to transform the target matrices into sparse matrices and calculate sparse matrix computations **on CPU.**
 - Considering the performance, sparse matrix - vector multiplications (SpMV) are used.
- In this study, we propose to calculate these sparse matrix computations **on GPU.**

How to calculate Sparse Matrix A - Matrix B multiplication?



Implementation Details of Accurate MMM Library (Ozaki Method)

1. Implementation by dgemm **1dgemm**
2. SpMV (Inner Parallel) with CRS format **2CRS**
3. SpMV (Outer Parallel) with CRS format **3CRS**
4. SpMV (Multiple RHS, Inner Parallel) with CRS format **4CRS**
5. SpMV (Multiple RHS, Inner Parallel (Blocking)) with CRS format **5CRS**
6. SpMV (Inner Parallel) with ELL format **6ELL**
7. SpMV (Outer Parallel) with ELL format **7ELL**
8. SpMV (Multiple RHS, Inner Parallel) with ELL format **8ELL**
9. SpMV (Multiple RHS, Inner Parallel (Blocking)) **9ELL**
10. Implementation by Batched BLAS **10GPU**
11. Implementation by dgemm (GPU) **11GPU**
12. SpMV with CRS format (GPU) **12GPU**
13. SpMV with ELL format (GPU) **13GPU**
14. SpMM with CRS format (GPU) **14GPU**

Experimental Environment



- ▶ **Supercomputer “Flow” Typell Subsystem**

Information Technology Center, Nagoya University

- ▶ CPU

- ▶ Intel Xeon Gold 6230, 20 Cores, 2.10 - 3.90 GHz x 2 Sockets

- ▶ GPU : Model generation for machine learning.

- ▶ NVIDIA Tesla V100 (Volta) SXM2, 2,560 FP64 Cores, up to 1,530 MHz x 4 Sockets

- ▶ **LIME** : ver. 0.2.0.1 (In this presentation, we skip this results.)

- ▶ **SHAP**: ver.0.39.0

- ▶ **Model of Machine Learning (Classifier)**

- ▶ **Random Forest Model** by scikit-learn ver. 0.24.1

- ▶ **11 Kinds of Implementations** are used.



How to generate test matrices

- ▶ Random matrices
- ▶ **Matrix #1** : Elements are generated by **0-1 region** for matrix A and B, then **insert a value with $\text{pow}(10, \text{rand}() \% \Phi)$** with respect to a sparsity.
 - ▶ Up to $\Phi=30$.
(If Φ is too large, then it cannot treat it by python.)
- ▶ **Matrix #2**: Elements are generated by **0-1 region** for matrix A and B **with respect to a sparsity**.
 - ▶ The sparsity is from **90% to 98%** in this experience.
- ▶ **Matrix #3** : Elements are generated by **Identity Matrix** for matrix A and B, then **insert a value with $\text{pow}(10, \text{rand}() \% \Phi)$** with respect to a sparsity.
 - ▶ Up to $\Phi=30$.
- ▶ **The random seed is fixed.**



Number of Learning Data and Prediction Accuracy

▶ Learning Data

1. **Matrix #1**: It can generate huge value of elements. The sparsity of almost 0.
2. **Matrix #2**: Sparse matrices with 0-1 range of elements.
3. **Matrix #3**: : It can generate huge value of elements. It can generate arbitrary sparsity.

▶ **Matrix size: 1000 – 4000.**

▶ Information for Machine Learning

▶ Model: **Random forest**

▶ **Explainable variables**: 7 variables

- ▶ 1)**Matrix size**; 2)**Sparsity of input matrix**; 3)**Maximum element of A**;
- 4)**Minimum element of A**; 5)**Number of split for sparse of A** ;
- 6)**Number of Split for dense of A**; 7)**Number of split for B**

▶ Number of learning (training) data: **199**

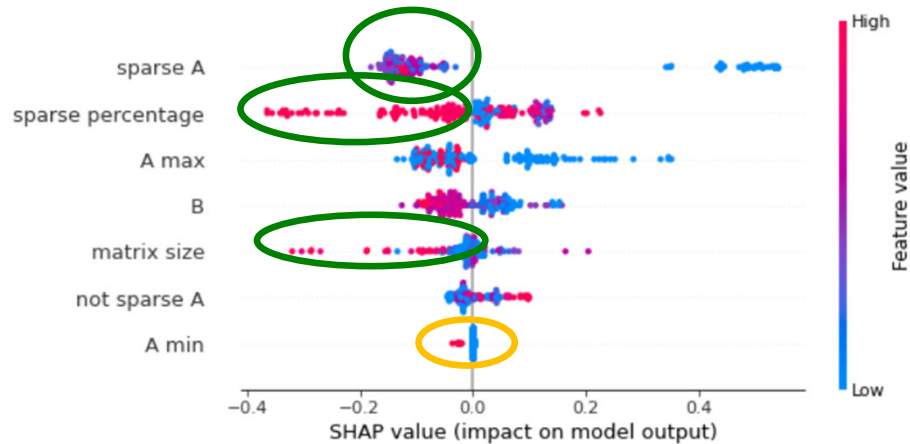
▶ Number of test data: **23**

▶ **Accuracy: 91.3%**

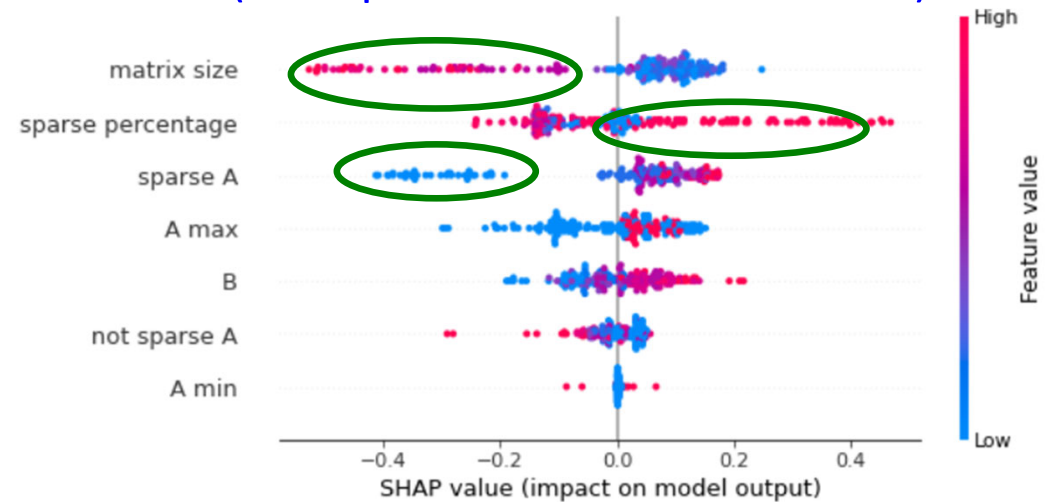
Analysis Result by SHAP

- Remarkable factors: (1) Absolute SHAP Value is large (Crucial Factor), (2) Same color and close (Same value of explainable variables), (3) Large cluster, or form a queue (Number of cases is large.)

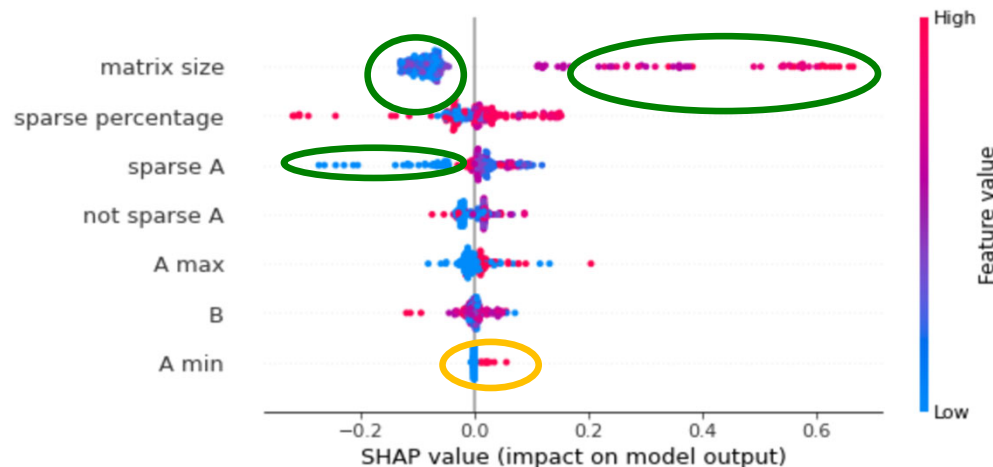
(1) Select: dgemm



(2) Select: SpMV with CRS format (Multiple RHS and Inner Parallel)



(3) Select: SpMM with CRS format (GPU)



Finding crucial factors:

- (1) **dgemm** : Number of splits for sparse of A (-), Sparsity of input matrix (-), Matrix sizes (-)
→ Reasonable
- (2) **CRS (SpMV)** : Matrix sizes (-), Sparsity of input matrix (+), Number of splits for sparse of A (-)
→ Reasonable
- (3) **CRS (SpMM)(GPU)** : Matrix sizes (-, +), Number of splits for sparse of A (-)
- Almost all element of minimal value for A is 0.
→ No effect. This is a NG explainable variable.

Closing Remarks

- ▶ **TOPIC I:** A Proposal of Mixed-Precision and/or Energy Optimization for ppOpen-AT.
 - ▶ Proposed an **AT framework (directive)** for optimization of mixed-precision computations and/or energy
 - ▶ **Future work**
 - ▶ Evaluate several applications
 - ▶ Supply the system **as a tool** : It is useful to show history by changing target of parts in programs (variables/arrays, or blocks).
- ▶ **TOPIC II:** Explainable AI for Auto-tuning of Numerical Libraries.
 - ▶ Obtained **a case with reasonable explanation** on a numerical library.
 - ▶ **Future work:** Propose AT method **to reduce AT time**, or **select better expandable variables** automatically.

